## EXISTING

 INTIME



## CODE

More situated in time than linear media or static artifacts


# CODE 

More situated in time than linear media or static artifacts


## Coob Music <br> Symbols for representing time



# Coom Music <br> Symbols for structuring execution 

LOOP DELIMITER SYMBOL


REPEAT SECOND SECTION, USE ALTERNATE ENDING SECOND TIME

# CoDE MUSIC 

Simple outline can be decoded in sophisticated way by specially-trained agents aka 'musicians'


Medium Swinging Latin $d=105 \square{ }^{6}$



## Krzysztof Penderecki: Threnody for the Victims of Hiroshima (1960)


*) flageolet tones



https://www.moma.org/explore/inside_out/2012/12/21/exhibiting-fluxus-keeping-score-in-tokyo-1955-1970-a-new-avant-garde/



A. (i) (3) $t$ Edt - Funcon

+     + 















## EASING

Smoothly transition a variable from one value to another in a set time

## SIMULATION

Use physics or other rules to determine next frame for one or more objects.

## TIMELINES

Schedule code for execution in the future

EASING

## Quadratic Easing

Flash's Timeline tweens use something called quadratic easing-which could actually be termed "normal" easing. The word quadratic refers to the fact that the equation for this motion is based on a squared variable, in this case, $t^{2}$ :

## $p(t)=t^{2}$

NOTE: I olwoys wondered why the term quadratic (the prefix meons "four") is used to describe equations with 0 degree of two ( $x^{2}$ ). While witing this chapter, I finally looked it up in the dictionary (RTFD, you might say). I discovered that quad originally refered to the four sides of o square. Thus, a squered vorible is quadrati.

I used the quadratic easing curve earlier in Figure 7-4. It's actually half a parabola. Here it is again, for reference purposes, in Figure 7-7

Here's the quadratic ease-in ActionScript function:

```
Math.easeInQuad = function (t, b, c, d) {
```

    return \(c^{*}(t /=d) * t+b ;\)
    \};

Recall that $t$ is time, $b$ is beginning position, $c$ is the total change in position, and $d$ is the duration of the tween.
This equation is more complex than the linear tween, but it's the
simplest of the equations that implement easing. Basically, I normalize $t$ by dividing it by d . This forces $t$ to fall between 0 and 1 . I multiply $t$ by itself to produce quadratic curvature in the values. Then I scale the value from a


## FIGURE 7.7

Groph of quadratic eosing
Robert Penner's

## ROBERT PENNER

Easing functions specify the rate of change of a parameter over time.
Objects in real life don't just start and stop instantly, and almost never move at a constant speed. When we open a drawer, we first move it quickly, and slow it down as it comes out. Drop something on the floor, and it will first accelerate downwards, and then bounce back up after hitting the floor. This page helps you choose the right easing function.

easelnElastic

easeOutElastic

easelnOutSine

easelnOutQuint




easelnExpo


easelnBounce




easeOutBounce
© Open Source
Help translate site to your language





EASIN Smoothly transition a variable from one value to another in a set time






## ROBERT PENNER

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## FIGURE 7.7

Groph of quadratic eosing
Robert Penner's






 Symblead $=$








SIMULATION

## SMUAATIN Use physics or other rules to determine next frame for one or more objects.



Craig Reynolds' Boids (1986)


Robert Hodgin's (Flight 404) Magnetosphere, 2007



$$
y^{p}
$$



$$
\mathrm{T}=3
$$



\#include "cinder/Rand.h"
\#include "cinder/Sphere.h"
\#include "Particle.h"
using namespace ci;
Particle::Particle()\{\}
Particle::Particle( const Vec3f \&pos, float charge )
: mPos( pos ), mCharge( charge )
mVel $=$ Vec3f::zero();
mAcc $\quad=$ Vec3f::zero();
mForce
$=0.0 f$;
$=1.0 f ;$
mShellRadius $=12.0 f$;
\}
void Particle::update( const Camera \&cam, float dt )
Acceleration is sum of forces acting on particle Add acceleration to velocity
Add velocity to position
$=$ Sphere( mPos, mRadius * 10.0f) ;
= cam.worldToScreen( mPos, app::getWindowWidth(), app::getWindowHeight() );
mVel += mAcc * dt;
mPos += mVel * dt;
mAcc = Vec3f::zero();
mVel $+=$ mAcc $* d t ;$ mPos $+=$ mVel $* d t$; mAcc = Vec3f::zero();
mShellRadius $=$ mRadius + fabs( mForce ) * 500ga of:
mMatrix.setToIdentity();
mMatrix.translate( mPos );
"The physics of the simple vehicle model is based on forward Euler integration. At each simulation step, behaviorally determined steering forces (as limited by max_force) are applied to the vehicle's point mass. This produces an acceleration equal to the steering force divided by the vehicle's mass. That acceleration is added to the old velocity to produce a new velocity, which is then truncated by max_speed. Finally, the velocity is added to the old position:

```
    steering_force = truncate (steering_direction,
max_force) Acceleration is sum of forces acting on particle
    acceleration = steering_force / mass
    velocity = truncate (velocity + acceleration,
max_speed)
    position = position + velocity
```

The simple vehicle model maintains its velocity-aligned
local space by incremental adjustment from the previous
time step."


Pretty good source in-house

