EXISTING



Feddersen 2021 NYU/ITP











More situated in time than linear media or static artifacts



BRANCH



Refer to and alter source



CODE MUSIC

Situated in time, with loops and branches, but not self-referential

4 4	













1/8 NOTE 1/4 NOTE



1/4 REST

CORE MUSIC

Symbols for structuring execution

LOOP DELIMITER SYMBOL



REPEAT FIRST SECTION ONCE

REPEAT SECOND SECTION, USE ALTERNATE ENDING SECOND TIME



Simple outline can be decoded in sophisticated way by specially-trained agents aka 'musicians'











https://www.reedmaxson.com/graphic-scores.html



Krzysztof Penderecki: Threnody for the Victims of Hiroshima (1960)

y con. faw an l'air V VC 6 T T *1 " in trees titlet atter *1111 メメ×1 13 Zifnen refelo a cup. harry man 小山雅哲学的 . 1

Rite of Spring Score, Igor Stravinsky



La Cachucha, by Friedrich Albert Zorn (wikipedia)



https://www.moma.org/explore/inside_out/2012/12/21/exhibitingfluxus-keeping-score-in-tokyo-1955-1970-a-new-avant-garde/



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Score of Ice Spirits, Meredith Monk





berg LP [US] bloomberg.com/graphics/2015-paul-ford-what-is-code/

Let's Be

A computer is a clock with benefits. They all work the sa one step at a time: Tick, take a number and put it in box put it in box two. Tick, operate (an operation might be a two numbers and put the resulting number in box one. and if it is, go to some other box and follow a new set of



"A computer is a clock with benefits. They all work the same, doing secondgrade math, one step at a time: Tick, take a number and put it in box one. Tick, take another number, put it in box two. Tick, *operate* (an operation might be addition or subtraction) on those two numbers and put the resulting number in box one. Tick, check if the result is zero, and if it is, go to some other box and follow a new set of instructions."











Xiomi Watch 26Mhz Oscillator (probably) iFixIt

1 10

....

1.8

818

110

(11)) 1010

÷....

10.16

HALE HALE STORES.

-

10.00

1018

11



- LVPECL Differential Output
- Operating Range: 2.5 V ±5%, 3.3 V ±10%





XXX.XXXX = Output Frequency (MHz) = Assembly Location

ONSEMI A037L 707.35MHZ VCX0



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	▶ Closure
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EASING

SIMULATION

Use physics or other rules to determine next frame for one or more objects.

TIMELINES

Schedule code for execution in the future

Smoothly transition a variable from one value to another in a set time



ROBERT PFNNFR

Quadratic Easing

Flash's Timeline tweens use something called *quadratic easing*—which could actually be termed "normal" easing. The word quadratic refers to the fact that the equation for this motion is based on a squared variable, in this case, t^2 :

 $p(t) = t^2$



NOTE: I always wondered why the term quad-ratic (the prefix means "four") is used to describe equations with a degree of two (x^2) . While writing this chapter, I finally looked it up in the dictionary (RTFD, you might say). I discovered that quad originally referred to the four sides of a square. Thus, a squared variable is quadratic.

I used the quadratic easing curve earlier in Figure 7-4. It's actually half a parabola. Here it is again, for reference purposes, in Figure 7-7. Here's the quadratic ease-in ActionScript function:

```
Math.easeInQuad = function (t, b, c, d) {
    return c^{(t/=d)}t + b;
};
```

Recall that t is time, b is beginning position, c is the total change in position, and d is the duration of the tween. This equation is more complex than the linear tween, but it's the simplest of the equations that implement easing. Basically, I normalize t by dividing it by d. This forces t to fall between 0 and 1. I multiply t by itself to produce quadratic curvature in the values. Then I scale the value from a

FIGURE 7-7 Graph of quadratic easing



Robert Penner's Programming Macromedia Flash (2002)

← → C (a https://easings.net/en



https://easings.net/en



PROGRESS



100% 1.0

VALUE

0



PROGRESS



100% 1.0

VALUE

0







VALUE

0





← → C (a https://easings.net/en



https://easings.net/en

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https://greensock.com/ease-visualizer





SIMULATION

SIMULATION Use physics or other rules to determine next frame for one or more objects.



Craig Reynolds' Boids (1986)

Robert Hodgin's (Flight 404) Magnetosphere, 2007



$\mathbf{T} = \mathbf{0}$

Acceleration is sum of forces acting on particle Add acceleration to velocity Add velocity to position

T = 1



T = 2



T = **3**







Can be expanded to three dimensions, multiple particles, and attractive and repulsive forces. But the steps between frames will remain basic vector addition.

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http://roberthodgin.com/project/magnetosphere

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Sources

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COPARTICLE

```
// Created by Robert Hodgin on 5/14/12.
       Copyright (c) 2012 __MyCompanyName__. All rights reserved.
 6 //
    11
 7
    #include "cinder/app/AppBasic.h"
 9
    #include "cinder/Rand.h"
10
    #include "cinder/Sphere.h"
11
    #include "Particle.h"
12
13
    using namespace ci;
14
15
    Particle::Particle(){}
16
17
    Particle::Particle( const Vec3f &pos, float charge )
18
            : mPos( pos ), mCharge( charge )
19
20 {
                                 = Vec3f::zero();
21
            mVel
                                 = Vec3f::zero();
22
            mAcc
23
                                  = 0.0f;
            mForce
24
25
            mRadius
                                  = 1.0f;
26
            mShellRadius
                          = 12.0f;
27
28
    void Particle::update( const Camera &cam, float dt )
29
                                                                                                                     Add acceleration to velocity
30
                                                                                                                     Add velocity to position
                                  = Sphere( mPos, mRadius * 10.0f );
31
            Sphere s
                                  = cam.worldToScreen( mPos, app::getWindowWidth(), app::getWindowHeight() );
32
            mScreenPos
                          = cam.getScreenRadius( s, app::getWindowWidth(), app::get
33
            mScreenRadius
                                                                                                                                             - menarye * V.JI
                                                                                                         IIICO COT
                                                                                       JJ
34
                                                                                      36
                                  = mCharge * 0.5f + 0.5f;
            mColor
35
36
                                                                                                         mVel += mAcc * dt;
                                                                                      37
37
            mVel += mAcc * dt;
                                                                                                         mPos += mVel * dt;
                                                                                      38
38
            mPos += mVel * dt;
39
            mAcc = Vec3f::zero();
                                                                                                         mAcc = Vec3f::zero();
                                                                                      39
40
41
            mShellRadius = mRadius + fabs( mForce ) * 50000.0f;
                                                                                      40
42
                                                                                                          mchallDadius - mDadius : faha/ mEanas )
                                                                                       11
            mMatrix.setToIdentity();
            mMatrix.translate( mPos );
44
45 }
46
    void Particle::draw()
47
48
            gl::color( Color( mColor, mColor, mColor ) );
49
            gl::drawSphere( mPos, mRadius );
50
```

Acceleration is sum of forces acting on particle

https://github.com/flight404/Eyeo2012



"The physics of the simple vehicle model is based on forward Euler integration. At each simulation step, behaviorally determined steering forces (as limited by max force) are applied to the vehicle's point mass. This produces an acceleration equal to the steering force divided by the vehicle's mass. That acceleration is added to the old velocity to produce a new velocity, which is then truncated by max speed. Finally, the velocity is added to the old position:

steering_force = truncate (steering_direction, max force) acceleration = steering force / mass velocity = truncate (velocity + acceleration, max speed) position = position + velocity

The simple vehicle model maintains its velocity-aligned local space by *incremental adjustment* from the previous time step."

Acceleration is sum of forces acting on particle Add acceleration to velocity Add velocity to position

Steering Behaviors For Autonomous Characters Craig W. Reynolds https://www.red3d.com/cwr/steer/gdc99/





https://www.youtube.com/watch?v=qMq-zd6hguc&list=PLRqwX-V7Uu6bR4BcLjHHTopXItSjRA7yG

Pretty good source in-house